

Life is Random, Time is Not

Markov Decision Processes with Window Objectives

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Strategy synthesis

Finding good controllers for systems interacting with an environment

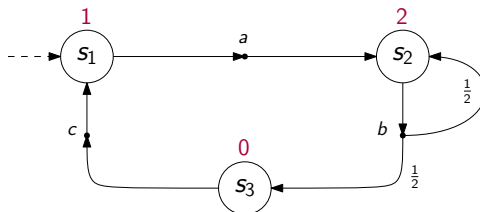
- **Game setting:** ensure a specified behavior against all possible strategies of the environment
- **Markov Decision Process (MDP) setting:**
 - environment **stochastic**
 - ensure a specified behavior with a sufficient probability
- **Classical objectives** reason about infinite runs *in their limit*
- **Window objectives in games** [CDRR15, BHR16]: *ensure a good behavior in a parametrized time frame all along the run*
 - ↪ conservative approximations of classical objectives

Aim of this talk

Introducing **window objectives** in the **stochastic** context

Example

- **Parity**: asks the **minimum priority seen infinitely often to be even**
 - ↪ canonical way of encoding ω -regular properties
 - ↪ controller winning

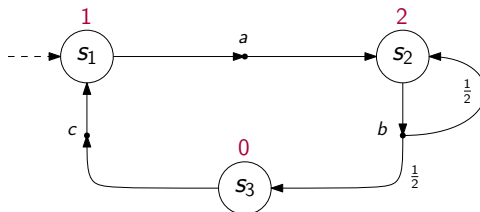


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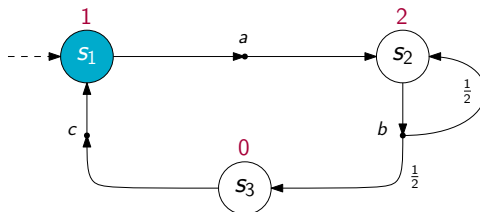
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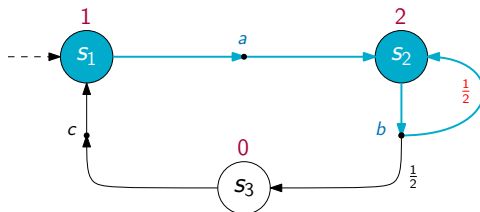
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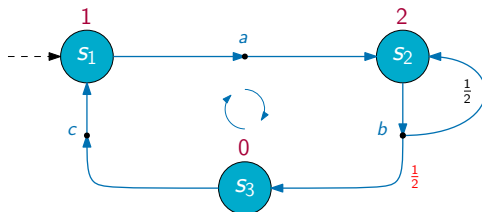
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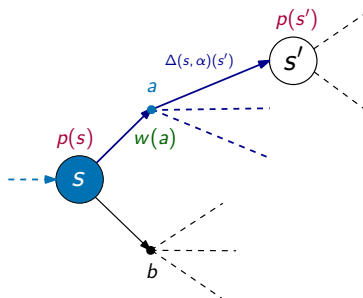
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↪ probability zero

Outline

- 1. Model
- 2. Objectives
 - 2.1 Classical long-run objectives
 - 2.2 Window objectives
 - 2.3 Direct case
 - 2.4 Prefix independent variants
 - 2.5 Decision problem
- 3. Fixed case
 - 3.1 Reductions
 - 3.2 Direct fixed window
- 4. Prefix independent objectives
 - 4.1 The case of end-components
 - 4.2 Fixed and Bounded window

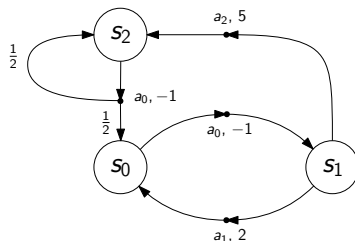
Markov Decision Process (MDP)



An MDP $\mathcal{M} = (S, A, \Delta)$ is a tuple such that

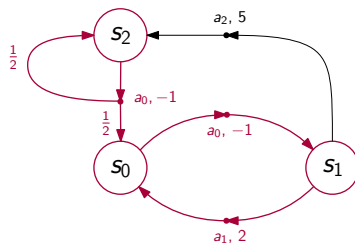
- S is the **set of states** of the system
- A is the **set of actions** of the system
- $\Delta : S \times A \rightarrow \mathcal{D}(S)$ is the **probability transition function**
- $w : A \rightarrow \mathbb{Z}$ is a **weight function**
- $p : S \rightarrow \{0, 1, \dots, d\}$ is a **priority function** ($d \leq |S| + 1$ w.l.o.g.)

Runs and strategies



- **Runs:** $\rho = s_0 \xrightarrow{a_0} s_1 \xrightarrow{a_1} s_2 \dots s_n \xrightarrow{a_n} \dots \in \text{Runs}(\mathcal{M})$ such that $\Delta(s_i, a_i)(s_{i+1}) > 0$
- **Strategy:** σ chooses at each step an action
 - **pure finite-memory strategies:** choose actions according to a finite amount of information gathered in the past
 - **pure memoryless strategies:** $\sigma : S \rightarrow A$

Runs and strategies



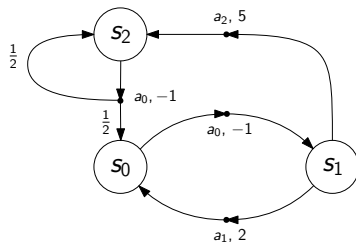
- Fix a strategy σ
- Induce a *discrete-time Markov chain*: fully stochastic process \mathcal{M}^σ
 - ⇒ **Event**: $E \subseteq \text{Runs}^\sigma(\mathcal{M})$
 - ⇒ $\mathbb{P}_{\mathcal{M}}^\sigma[E]$: probability measure of the event E

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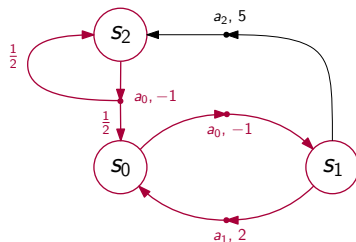
Long-run objectives

- **Parity** = $\{\rho \in \text{Runs}(\mathcal{M}) \mid \min_{s \in \text{inf}(\rho)} p(s) = 0 \pmod{2}\}$
- **MeanPayoff** = $\{\rho \in \text{Runs}(\mathcal{M}) \mid \text{MP}(\rho) \geq 0\}$
 - $\text{MP}(\rho = s_0 \xrightarrow{a_0} s_1 \xrightarrow{a_1} \dots) = \liminf_{n \rightarrow \infty} \frac{1}{n} \cdot \sum_{i=0}^n w(a_i)$
 - **Example:** $\forall n \in \mathbb{N}$,
 $\text{MP}((s_2 \xrightarrow{a_0})^n (s_0 \xrightarrow{a_0} s_1 \xrightarrow{a_1})^\omega) = \text{MP}((s_0 \xrightarrow{a_0} s_1 \xrightarrow{a_1})^\omega) = \frac{1}{2}$



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 - $\mathbb{P}_{\mathcal{M}, s_2}^\sigma [\text{MeanPayoff}] = 1$



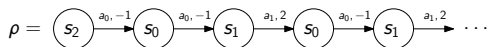
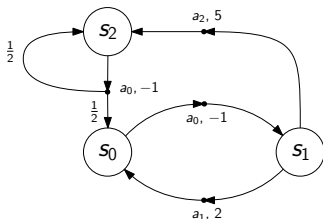
Window Objectives

- Runs that exhibit **good behaviors** within a configurable **time frame**
 - Strengthen traditional objectives** (correct behaviors at the limit)
- ~ Make use of the **window formalism** to reason about **behaviors** in a given time bound $\lambda > 0$.

$$GW(\lambda) = \{\rho \in \text{Runs}(\mathcal{M}) \mid \text{good behavior in at most } \lambda \text{ steps from } s_0\}$$

- Positive sum in at most $\lambda = 3$ steps?

Window Mean-Payoff

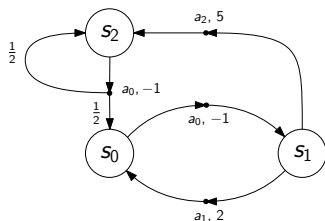


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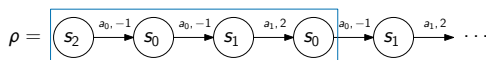
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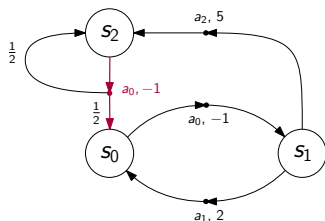


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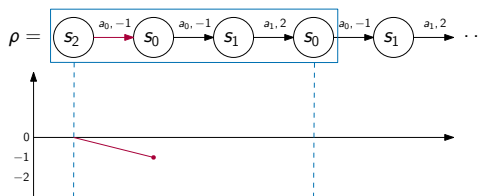
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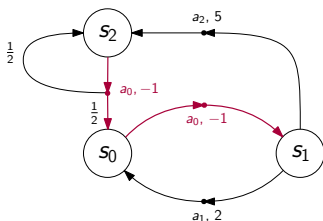


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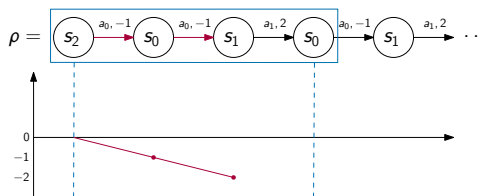
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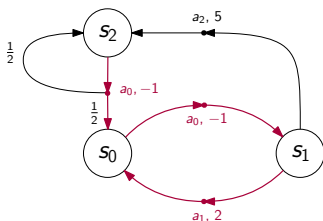


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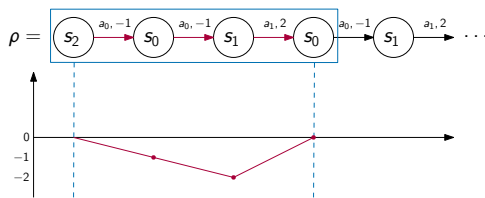
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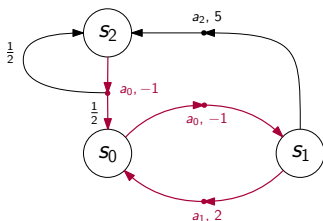
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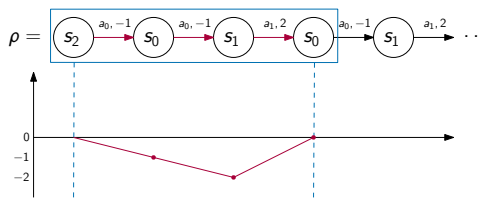
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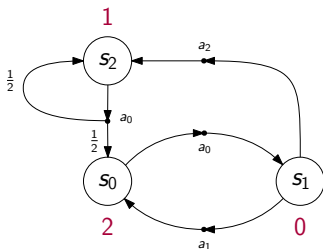
↪ $\rho \in GW_{mp}(3)$

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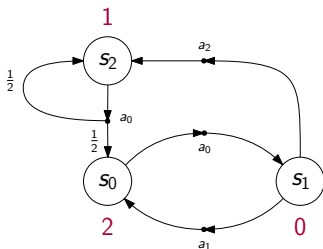


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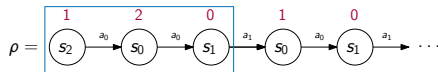
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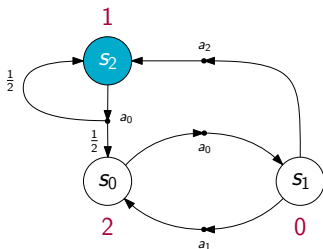


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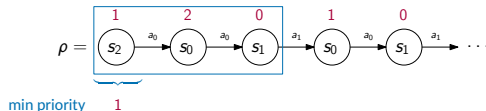
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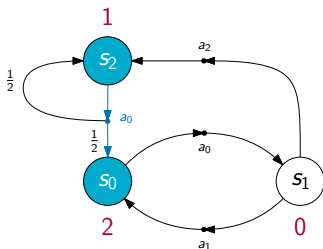


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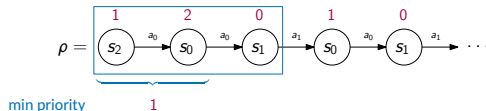
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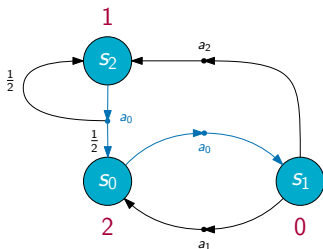


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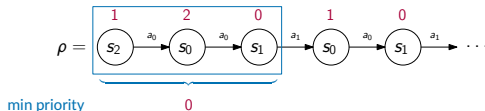
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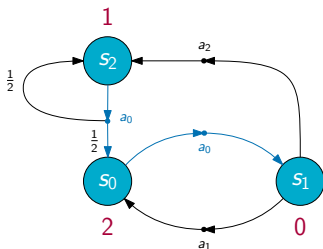
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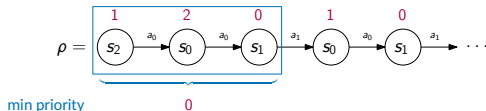
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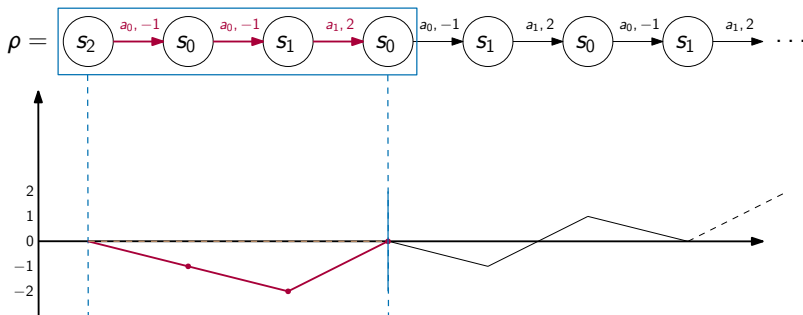


- ↪ Good window of size $\lambda = 3$
- ↪ $\rho \in GW_{\text{par}}(3)$

Window Objectives: Direct Fixed Window

- Fix a window size $\lambda > 0$
- Direct Fixed Window objective:** $\text{DFW}(\lambda) \equiv \Box \text{GW}(\lambda)$
- Good Window** of maximal size λ **sliding along the run**

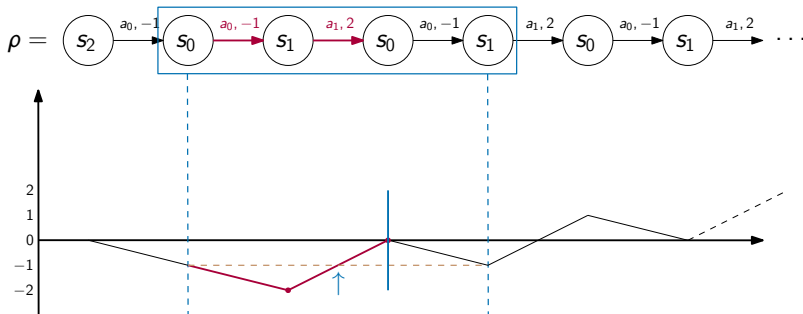
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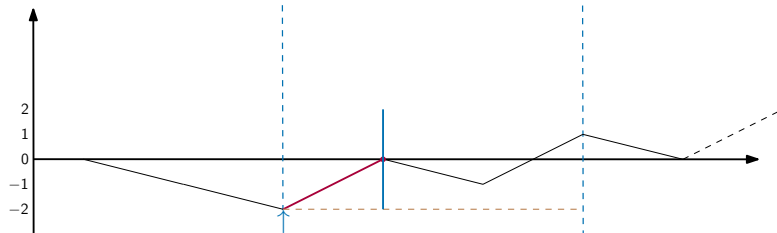
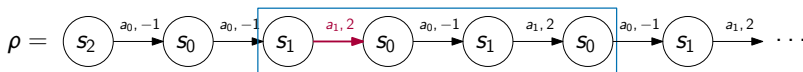
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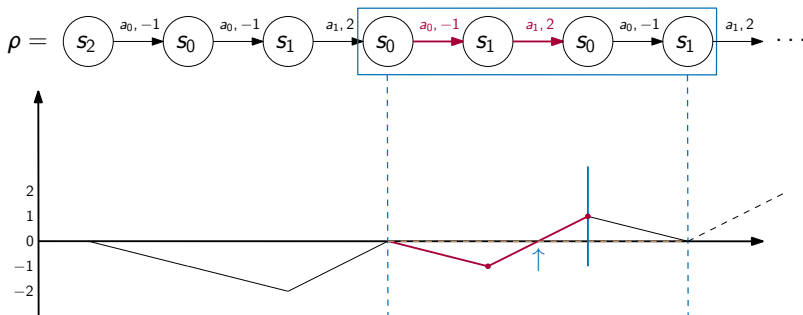
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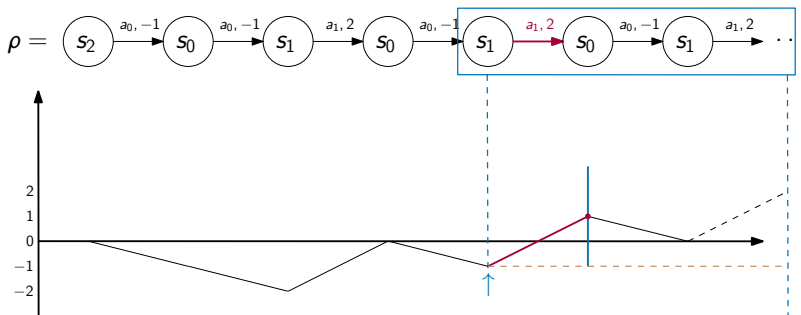
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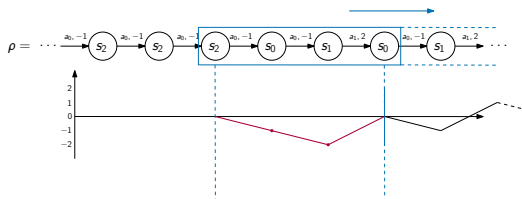
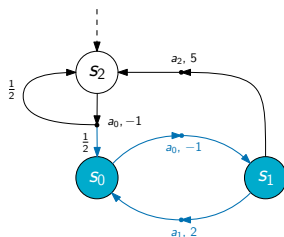
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Window Objectives: prefix independence

- Window objectives at the limit
- Fixed Window objective:** $\text{FW}(\lambda) \equiv \Diamond \text{DFW}(\lambda) \equiv \Diamond \Box \text{GW}(\lambda)$
- Bounded Window objective:** $\text{BW} \equiv \exists \lambda > 0, \text{FW}(\lambda)$

$$\rho = (s_2 \xrightarrow{a_0})^+ (s_0 \xrightarrow{a_0} s_1 \xrightarrow{a_1})^\omega \in \text{FW}(3) \cap \text{BW}$$



Threshold Probability Problem

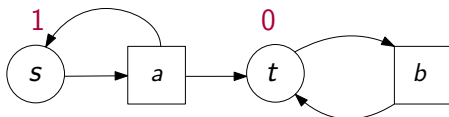
Given

- an **MDP** \mathcal{M} with state space S ,
- a **maximal window size** $\lambda > 0$,
- an initial **state** $s \in S$,
- a **window objective** $\mathbb{O} \in \{\text{DFW}(\lambda), \text{FW}(\lambda), \text{BW}\}$ for mean-payoff or parity and
- a **probability threshold** $\alpha \in [0, 1] \cap \mathbb{Q}$,

decide if

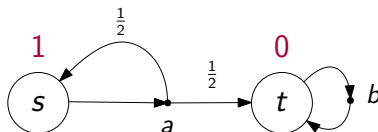
$$\exists ? \sigma \quad \mathbb{P}_{\mathcal{M}, s}^{\sigma}[\mathbb{O}] \geq \alpha$$

Window Games



$\exists \sigma_{\bigcirc} \forall \sigma_{\square}, \rho = \text{Outcome}(s, \sigma_{\bigcirc}, \sigma_{\square}) \in \text{DFW}(\lambda)$

- **Existence of a uniform bound λ^* on the maximal window size**
- \bigcirc is loosing for all λ since \square can choose $a \rightarrow s$



$\exists \sigma, \mathbb{P}_s^{\sigma}[\text{DFW}(\lambda)] \geq \alpha$

- **no uniform bound on the maximal window size**
- For $\lambda > 1$, $\mathbb{P}_s[\text{DFW}(\lambda)] = 1 - \frac{1}{2^{\lambda-1}}$
- $\mathbb{P}_s[\text{DFW}(3)] = \Delta(s, a)(t) + \Delta(s, a)(s') \cdot \Delta(s, a)(t) = \frac{1}{2} + \frac{1}{4} = \frac{3}{4}$

Results overview

Markov Decision Processes

		parity		mean-payoff	
		complexity	memory	complexity	memory
DFW	P-c.	polynomial		EXPTIME/PSPACE-h.	pseudo-polynomial
FW				P-c.	polynomial
BW		memoryless		$NP \cap coNP$	memoryless

Games [CDRR15, BHR16]

		parity		mean-payoff	
		complexity	memory (\mathcal{P}_1)	complexity	memory (\mathcal{P}_1)
DFW	P-c.	polynomial		P-c.	polynomial
BW					
FW		memoryless		$NP \cap coNP$	memoryless

Outline

1. Model

2. Objectives

2.1 Classical long-run objectives

2.2 Window objectives

2.3 Direct case

2.4 Prefix independent variants

2.5 Decision problem

3. Fixed case

3.1 Reductions

3.2 Direct fixed window

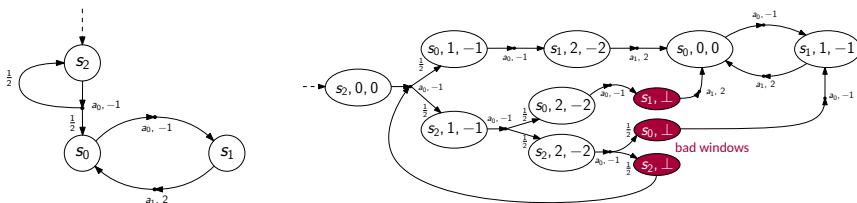
4. Prefix independent objectives

4.1 The case of end-components

4.2 Fixed and Bounded window

Strategies: memory requirements

- **Pure finite memory strategies** are sufficient
- **Main tools:** natural reduction from DFW to **safety** and FW to **co-Büchi**
- **unfolding** based on the maximal window size λ



- **Idea:** incorporate **weights (resp. priorities)** as well as the **current number of steps in the state space** of the MDP
- **Mean-payoff:** $S \times \{0, 1, \dots, \lambda\} \times \{-\lambda \cdot W, \dots, 0\}$
- **Parity:** $S \times \{0, 1, \dots, \lambda\} \times \{0, 1, \dots, d\}$

Complexity and memory requirements

DFW	
Mean-Payoff	Parity
Threshold probability problem	
<ul style="list-style-type: none"> • EXPTIME algorithm • Pseudo-polynomial-memory optimal strategies • PSPACE-hard [HK15] • Pseudo-polynomial-memory strategies necessary 	<ul style="list-style-type: none"> • P algorithm • Polynomial-memory optimal strategies • P-hard [Bee80, Imm81] • Polynomial-memory strategies necessary

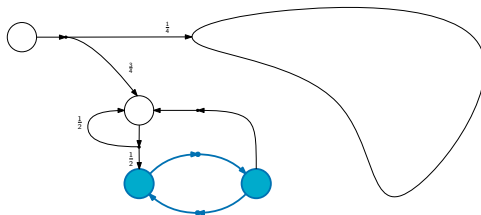
Outline

- 1. Model
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 - 4.1 The case of end-components
 - 4.2 Fixed and Bounded window

End-component

Let \mathcal{M} be an MDP, an **end-component (EC)** is a **strongly connected** sub-MDP \mathcal{C} of \mathcal{M} formed by states and actions allowing to never leave \mathcal{C}

- For any strategy σ , all runs ρ compatible with σ end up in an EC with probability one



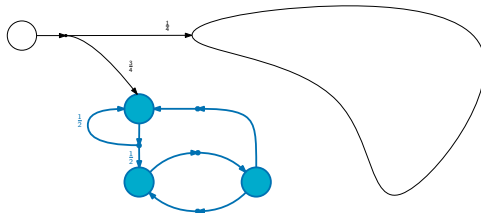
End-component

Let \mathcal{M} be an MDP, an **end-component (EC)** is a **strongly connected** sub-MDP \mathcal{C} of \mathcal{M} formed by states and actions allowing to never leave \mathcal{C}

- The number of ECs may be exponential in the size of \mathcal{M}
- An EC may have sub-ECs
- the union of two ECs with non-empty intersection is an EC

⇒ **Maximal end-component (MEC)** = ECs that cannot be extended

⇒ MEC(\mathcal{M}) computable in polynomial time



MEC classification and Zero-one Law

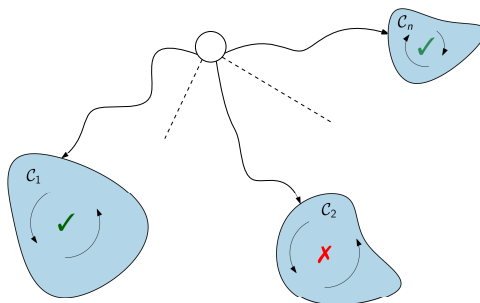
- **Prefix independence** \rightsquigarrow MECs analysis
- **Main result:** *MEC classification*
- **strong link between ECs and 2 player games**

\rightsquigarrow 2 types of MECs: ✓ and ✗

Given an objective $\mathbb{O} \in \{\text{FW}(\lambda), \text{BW}\}$

✓ $\forall s \text{ of } \mathcal{C} \exists \sigma, \mathbb{P}_{\mathcal{C},s}^{\sigma}[\mathbb{O}] = 1$

✗ $\forall s \text{ of } \mathcal{C} \forall \sigma, \mathbb{P}_{\mathcal{C},s}^{\sigma}[\mathbb{O}] = 0$

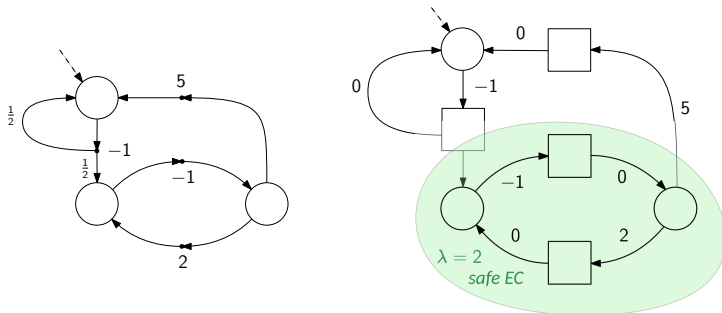


Safe EC

An EC \mathcal{C} of state space $S_{\mathcal{C}}$ is λ -safe iff $\forall s \in S_{\mathcal{C}}$,
 $\exists \sigma \forall \rho \in \text{Runs}^{\sigma}(\mathcal{C}), \rho \in \text{DFW}(\lambda)$

↪ Boils down to interpreting \mathcal{C} as a 2 player game

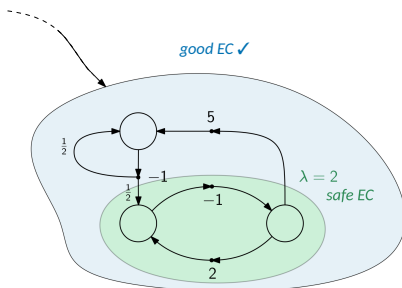
- $\exists ?\mathcal{C}, \lambda$ -safe EC inside a super-EC \mathcal{C}^*
 - compute the winning set \mathcal{W}_{dfw} of the DFW game version of \mathcal{C}^*
 - $\mathcal{W}_{\text{dfw}} \neq \emptyset \implies \exists \lambda$ -safe EC \mathcal{C} inside \mathcal{C}^*



Good EC

An EC \mathcal{C} is

- ✓ λ -good for $\lambda > 0$ if it contains a sub-EC \mathcal{C}' which is λ -safe
- ✓ BW-good if it contains a sub-EC \mathcal{C}' which is λ -safe for some $\lambda > 0$



- In all EC \mathcal{C} , $\exists \sigma_{\text{visit}}^{\mathcal{C}}$ allowing to visit with probability one all states of \mathcal{C}

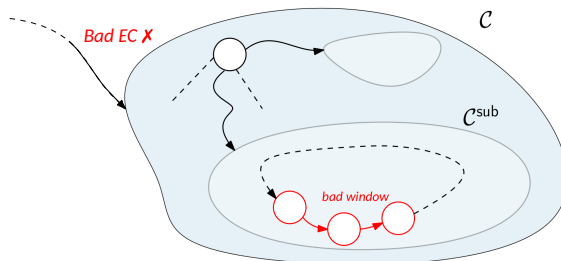
$$\Rightarrow \mathbb{P}_{\mathcal{C}}^{\sigma_{\text{visit}}^{\mathcal{C}}}(\Diamond \mathcal{C}_{\text{safe}}) = 1$$

- $\sigma_{\checkmark} = \text{combine } \sigma_{\text{visit}}^{\mathcal{C}} \text{ and } \sigma_{\text{safe}}$

$$\Rightarrow \mathbb{P}_{\mathcal{C}}^{\sigma_{\checkmark}}[\mathbb{O}] = 1 \text{ for } \mathbb{O} \in \{\text{FW}(\lambda), \text{BW}\}$$

Bad EC ?

- \nexists safe sub-EC inside the 2PG version of \mathcal{C} ?
- Fix any finite-memory strategy σ inside \mathcal{C}
- The set of states and actions seen infinitely often form sub-ECs \mathcal{C}^{sub} with probability one
- In these sub-ECs \mathcal{C}^{sub} , $\exists \rho \notin \text{DFW}(\lambda)$ (otherwise \mathcal{C}^{sub} is safe)
- extract a bad prefix ρ^x (=bad window) in ρ
- ρ^x is repeated infinitely often with probability one in \mathcal{C}^{sub}
- $\forall \mathcal{C}^{\text{sub}}, \mathbb{P}_{\mathcal{C}^{\text{sub}}}^{\sigma}[\text{DFW}(\lambda)] = 0 \implies \mathbb{P}_{\mathcal{C}}^{\sigma}[\mathbb{O}] = 0 \quad \mathbb{O} \in \{\text{FW}(\lambda), \text{BW}\}$



Summary: complexity and strategies

Given $\mathbb{O} \in \{\text{FW}(\lambda), \text{BW}\}$, 2 types of MECs: ✓ and ✗

✓ $\forall s \text{ of } \mathcal{C} \exists \sigma, \mathbb{P}_{\mathcal{C},s}^{\sigma}[\mathbb{O}] = 1$

✗ $\forall s \text{ of } \mathcal{C} \forall \sigma, \mathbb{P}_{\mathcal{C},s}^{\sigma}[\mathbb{O}] = 0$

MEC classification

Mean-Payoff

Parity

Fixed window (FW)

- in P (2PG)

- in P (2PG)

- pure polynomial finite-memory strategy $\sigma_{\checkmark} := \sigma_{\text{visit}}^{\mathcal{C}} + \sigma_{\text{safe}}$

Bounded window (BW)

- in $\text{NP} \cap \text{coNP}$ (2PG)

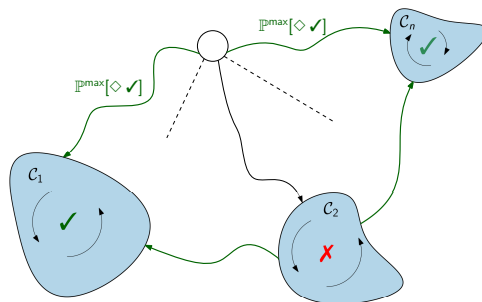
- in P (2PG)

- pure memoryless strategy $\sigma_{\checkmark} := \sigma_{\text{visit}}^{\mathcal{C}} + \sigma_{\text{safe}}$

Optimal strategies for FW and BW

$$\sigma_{\diamond\checkmark}^{\max} = \arg \max_{\sigma} \mathbb{P}^{\sigma}[\diamond\checkmark]$$

$$\sigma^* := \underbrace{\sigma_{\diamond\checkmark}^{\max}}_{\text{until reaching } \checkmark} + \underbrace{\sigma_{\checkmark}}_{\text{in } \checkmark}$$



Summary

Back to the results overview

Markov Decision Processes

		parity		mean-payoff	
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DFW	P-c.	polynomial	memoryless	EXPTIME/PSPACE-h.	pseudo-polynomial
FW				P-c.	polynomial
BW				$NP \cap coNP$	memoryless

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Extensions

- **Expected window size:** strategies maintaining the best time bounds possible in their local environment
 - $\min_{\sigma} \mathbb{E}_{\mathcal{M}}^{\sigma}[\lambda] = \min_{\sigma} \sum_{\lambda > 0}^{\infty} \lambda \cdot \mathbb{P}_{\mathcal{M}}^{\sigma}[\text{FW}(\lambda) \setminus \text{FW}(\lambda - 1)]$
 - **Refine the classification process:** identify best window size λ in each MEC by binary search
 - **Contract each good MEC and assign λ as entering weight**
- **Multi window objectives:**
 - DFW: extend the unfolding for multiple dimensions
 - **MEC classification:** games with multiple window objectives
- **Tool support: implementation in STORM**
 - + DFW, FW and BW objectives for parity and mean-payoff
 - + Efficient unfoldings for DFW
 - + Window games for parity [BHR16] and mean-payoff [CDRR15]
 - + Total payoff games: efficient pseudo-polynomial time algorithm with value iteration [BGHM14]
 - + Weak parity games [CHH09]
 - + Rich MEC classification methods
 - + Strategy synthesis (export in .dot format)